



microEnable 5

## marathon ACL/VCL

...for most Established Machine Vision Standard  
with Outstanding Price-/Performance Ratio

### What you need to know:

- ◆ Frame grabber series with Camera Link interface - compliant with Camera Link standard 2.0
- ◆ Extended cable length
- ◆ Plug ,n' Plug real-time image and signal processing
- ◆ A-Series with comprehensive set of on-board image processing functions: LUT, ROI, De-Bayering, shading correction, noise filter and more in pre-defined configurations
- ◆ Front GPIO (opto-isolated, 4,5–28V), TTL outputs for control, communication and synchronization
- ◆ Internal GPIO – interface with support for add-on GPIO board (requires additional slot)
- ◆ 100% compliant with Silicon Software SDK and GUI control and service tools
- ◆ Third-Party Vision tool interface: Halcon, Common Vision Blox and others
- ◆ marathon VCL with custom FPGA programming by VisualApplets supporting Xilinx Kintex FPGAs

**Please note:** microEnable 5 marathon ACL is not available now - coming soon!

## Technical Specification:

### Camera Interface

- ◆ Camera Link 2.0, GenICam GenTL
- ◆ Base, DualBase, Medium, Full, Deca modes
- ◆ PoCL SafePower, 4Watt/cable
- ◆ PixelClock: up to 85 MHz
- ◆ Extended cable length
- ◆ Camera Connection: 2x SDR Connectors
- ◆ Test Environment: Camera Simulator

### Onboard Memory

- ◆ marathon ACL : 512 MByte DDR3-RAM
- ◆ marathon VCL: 2 GByte DDR3-RAM

### V-Series Vision Processor (marathon VCL)

- ◆ Xilinx Kintex 7 XC7K160T

### Host Interface (DMA1800)

- ◆ PCIe x4, Gen2 (Direct Memory Access)
- ◆ Up to 1800 MB/s sustainable data bandwidth

### Physical and Environmental Properties

- ◆ PCIe standard height, half length card:  
167.64 mm length x 111.15 mm height
- ◆ Operating temperature: 0° to 50°, fanless
- ◆ Requires one x4 Gen2 PCIe slot
- ◆ ROHS, CE pending

### Controls and General-Purpose I/Os

*Internal GPIO Interface (for connection with trigger boards)*

- ◆ 8 opto-coupled inputs (4,5-28V), optional  
4 opto-coupled differential inputs (RS422)
- ◆ 8 opto-coupled outputs (4,5-28V)
- ◆ Shaft encoder input, programmable rescaler,  
multiple-camera synchronization

*Front-GPIO (HD SubD15 connector)*

- ◆ 2 opto-coupled differential inputs (RS422) and  
1 opto-coupled differential / single ended input;  
optional (conf.): 4 opto-coupled Inputs (4,5-  
28V) with up to 1 MHz frequency
- ◆ 2 TTL outputs, up to 20 MHz frequency
- ◆ Shaft encoder input, programmable rescaler
- ◆ Multiple-camera synchronization

### Software

- ◆ Windows 7 & 8 and Linux for 32/64bit
- ◆ Image acquisition control and viewer tool
- ◆ Camera control tool (GenICam)
- ◆ Service tool (test and firmware updates)
- ◆ Software API: SDK (C/C++ projects, .net  
interface)
- ◆ Vision tool interfaces: Halcon, CVB, VisionPro,  
Labview, MIL, others on request
- ◆ FPGA programming (marathon VCL) with  
VisualApplets

### Current Availability

- ◆ microEnable 5 marathon VCL

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